

THREE-CAVITY STABILIZED LASER SYSTEM

FIELD OF THE INVENTION

The present invention relates to lasers, and in particular to lasers stabilized
5 by selective wavelength feedback devices.

BACKGROUND OF THE INVENTION

Many lightwave systems require laser sources that output a stable wavelength over a narrow-band or a broad-band for a wide range of operating
10 conditions. For example, in certain telecommunication systems diode lasers are used to pump active elements (e.g., erbium-doped fiber amplifiers) over a wide range of temperatures and drive currents for long periods of time. The requirements on the operational stability of diode lasers as a function of temperature and drive current, as well as diode laser aging have become more demanding as the
15 performance requirements for the system as a whole have increased.

One approach to wavelength stabilization of a laser system is through frequency-selective feedback into the laser. By way of example, with reference to FIG. 1 there is shown a prior art two-cavity fiber Bragg grating stabilized diode laser system 10 comprising a diode laser 12 with rear and front facets 14 and 16, respectively. Front facet 16 has a reflectivity R_{FF} . Adjacent rear facet 14 is a rear-facet monitor (RFM) 20 that is used to monitor output power and provide feedback to control the drive current supplied to the diode laser to maintain a constant output power.

An optical fiber 26 is optically coupled to diode laser 12 at front facet 16. A
25 fiber Bragg grating 32 having a select reflectivity bandwidth (typically 1 nm or so) within the laser gain and a reflectivity R_G is formed in optical fiber 26 a distance D1 from front facet 16.

In system 10, there are two discrete Fabry-Perot cavities. One cavity is within the diode laser itself between rear facet 14 and front facet 16, while the
30 second cavity is an “external cavity” formed between the front facet and the fiber Bragg grating 32.

There are two main criteria for stable, broadband operation of system 10. The first is that the reflectivities R_{FF} and R_G need to be chosen such that the reflected light from the fiber Bragg grating is capable of causing system 10 to operate in what is known as the “coherence collapse” regime. From the analysis of 5 C. Henry and R.F. Karzarinov in their article “Instability of semiconductor lasers due to optical feedback from distant reflectors,” IEEE J. Quantum Electron., vol. QE-22, pp. 295-301, 1986, the relationship between the reflectivities R_{FF} and R_G for operation in the coherence collapse regime is:

10
$$R_G > (0.01)R_{FF} / (1-R_{FF})^2$$

This relationship is satisfied over a very broad range of reflectivities, including the case where $R_G \sim R_{FF}$. For the case of coupling to an optical fiber, the coupling efficiency can be folded into an effective front facet reflectivity R_{EFF}

15 The second criterion for stable operation of system 10 is that the distance $D1$ be greater than the coherence length L of the free running diode laser (i.e., in the absence of feedback from the fiber Bragg grating). This requirement ensures that the feedback light is incoherent with the light emitted from the diode laser. If the condition $D1 > L$ is not met, diode laser 12 experiences instabilities at semi-periodic 20 drive currents, which cause output power fluctuations (detected by RFM 20), which adversely impact the operation of the system (see, e.g., Achtenhagen et al, “L-I characteristics of fiber Bragg grating stabilized 980-nm pump lasers, IEE Photonics Technology Letters, Vol. 13, No. 5, May 2001).

The coherence length L depends on the characteristics of the laser, and can 25 be relatively large (i.e. greater than one meter). If the diode laser used is one that operates in a single longitudinal mode with a narrow bandwidth, the coherence length L can be relatively long, and substantially greater than that for a multi-longitudinal mode diode laser. A disadvantage of a large value of L is that the fiber Bragg grating must be placed very far away (e.g., meters) from the diode laser front 30 facet in order to obtain stable operation of the system over the drive current operating range.

Increasing the distance D1 to ensure coherence collapse operation can create two problems. First, the required distance D1 can become impractical, particularly in applications where space is a concern such as pumped amplifier systems. Second, bi-modal behavior of the system can result from polarization rotation of the 5 feedback light due to the natural birefringence in the fiber, which can be exacerbated by stressing or straining the fiber. This is particularly troublesome when D1 is large. For these reasons, it is preferred to keep the distance D1 as short as possible.

The problem of induced polarization rotation from fiber birefringence can be 10 overcome by using a polarization-maintaining fiber. Polarization-maintaining fiber is designed to maintain the polarization axis of the guided light independent of stress and strain in the fiber, which can lead to polarization rotation. While polarization-maintaining fiber was developed for use in fiber-based optical systems where polarization needs to be maintained, in the present application the use of such 15 fiber adds cost to the system and also makes the manufacturing process more complex because the fiber needs be precisely aligned to the diode laser during assembly.

SUMMARY OF THE INVENTION

20 A first aspect of the invention is a laser system that provides a stable output. The system includes a laser with front and rear ends surrounding a gain medium. A first wavelength-selective reflective element with a first reflectivity bandwidth is optically coupled to the laser. Optically coupled to the laser through the first wavelength-selective reflective element is a second wavelength-selective reflective 25 element with a second reflectivity bandwidth that at least partially overlaps the first reflectivity bandwidth. The first and second wavelength-selective reflective elements are arranged such that the laser exhibits stable operation in the coherence collapse regime.

In a second aspect of the invention, an optical system is used in the laser 30 system to couple the laser to the wavelength-selective reflective elements. The optical system may be arranged between the laser and the first wavelength-selective

reflective element, may encompass the first wavelength-selective reflective element only, the second wavelength-selective reflective element only, encompass both wavelength-selective reflective elements, or be arranged between the wavelength-selective reflective elements. The optical system may comprise an optical fiber, and

5 the wavelength-selective reflective elements may include fiber Bragg gratings or thin-film filters.

A third aspect of the invention is a method of forming a laser system that produces a stable output. The method includes providing a laser having an output end. First and second spaced apart wavelength-selective reflective elements having

10 at least partially overlapping reflectivity bandwidths are provided adjacent the output end. The first and second wavelength-selective reflective elements are then coupled to the output end to provide substantially incoherent optical feedback to the laser. The laser may include a diode laser with front and rear facets. Further, the first and second wavelength-selective reflective elements may include, for example,

15 thin-film filters arranged in free-space or fiber Bragg gratings arranged in an optical fiber as part of an optical system coupled to the laser.

A fourth aspect of the invention is a method of generating a stabilized laser output. The method includes providing a laser having rear and front ends surrounding a gain medium, and optically coupling the laser to first and second spaced apart wavelength-selective reflective elements. The elements have at least

20 partially overlapping reflectivity bandwidths and are arranged to provide incoherent optical feedback to the laser such that the laser generates a stable laser light output in a coherence collapse regime.

25

BRIEF DESCRIPTION OF THE DRAWINGS

FIG. 1 is a schematic diagram of a prior art two-cavity fiber Bragg grating laser system;

FIG. 2 is a schematic diagram of a three-cavity laser system that includes an optical system arranged between the laser and the first wavelength-selective

30 reflective element;

FIG. 3 is a schematic diagram of the laser system of FIG. 2, but with the optical system encompassing the first wavelength-selective reflective element;

FIG. 4 is a schematic diagram of the laser system of FIG. 2, but with the optical system arranged between the first and second wavelength-selective reflective elements;

FIG. 5 is a schematic diagram of the laser system of FIG. 2, but with the optical system encompassing the second wavelength-selective reflective element;

FIG. 6 is a schematic diagram of the laser system of FIG. 2, but with the optical system encompassing both wavelength-selective reflective elements;

10 FIG. 7 is a schematic diagram of the laser system of FIG. 6 wherein the optical system includes an optical fiber;

FIG. 8 is a close-up side cut-away view of the optical fiber of FIG. 7;

15 FIG. 9 is a plot of the operational modes (i.e., stable and unstable) of the laser system of FIG. 7 for various geometries as empirically determined by varying the distance D1 between the diode laser facet and the distance D3 between the fiber Bragg gratings;

FIG. 10 is a schematic diagram of an optical telecommunication system that includes the laser system of FIG. 7 for energizing an active element;

FIG. 11A includes plots of the output power (mW) versus drive current (mA) for three cases: (1) a two-cavity fiber Bragg grating laser system with a single grating having a power reflectivity $R_G = 3.4\%$ (dashed curve) and located a distance $D1 = 50$ cm, (2) a three-cavity fiber Bragg grating laser system having two gratings at a distance $D2 = 60$ cm (dotted curve), and (3) a two-cavity fiber Bragg grating laser system with a single grating having a power reflectivity of $R_G = 6.5\%$ (solid curve) and located a distance $D1 = 50$ cm; and

FIG. 11B includes plots of the RFM current (μ A) vs. drive current (mA) for the same three cases as in FIG. 11A.

DETAILED DESCRIPTION OF THE INVENTION

30 In the following detailed description of the embodiments of the invention, reference is made to the accompanying drawings that form a part hereof, and in

which is shown by way of illustration specific embodiments in which the invention may be practiced. These embodiments are described in sufficient detail to enable those skilled in the art to practice the invention, and it is to be understood that other embodiments may be utilized and that changes may be made without departing from the scope of the present invention. The following detailed description is, therefore, not to be taken in a limiting sense, and the scope of the present invention is defined only by the appended claims.

With reference now to FIG. 2, there is shown a stabilized laser system 50 that includes a laser 52 with rear and front ends 54 and 56, respectively, between which is a gain medium 57. In an example embodiment, laser 52 is a diode laser and rear and front ends 54 and 56 are rear and front facets of the laser, where the front facet 56 has a reflectivity R_{FF} . An example diode laser is a single quantum well device emitting light at or near 980 nm, and that operates (lases) in a single longitudinal mode in the absence of optical feedback (i.e., as a free-running diode laser). Further in an example embodiment, laser 52 has a very coherent output that would require a single wavelength-selective reflective element to be placed relatively far (e.g., 90 cm or greater) from front end 56 of the laser to obtain stable coherence collapse operation.

System 50 further includes a power supply 58 connected to laser 52 to pump gain medium 57 so that the laser can emit light at a given output power level. Where laser 52 is a diode laser, power supply 58 includes a drive current supply (source) that provides a current to drive the diode laser.

Adjacent rear end 54 is a monitor 60 that is optically coupled to the rear end and electrically connected to power supply 58. Monitor 60 is used to monitor output power of the laser and provide feedback in the form of an electrical signal representative of the laser output to power supply 58 so that the amount of power (e.g., current) supplied to the laser can be controlled in order to maintain a constant output power. Where laser 52 comprises a laser diode, monitor 60 is a rear-facet monitor (RFM).

Optically coupled to laser 52 at front end 56 via an optical system 66 are first and second wavelength-selective reflective elements 72 and 74 having

respective reflectivity bandwidths B1 and B2 within the gain bandwidth of laser 52. In an example embodiment, bandwidths B1 and B2 may range from about 0.1 nm to about 1 nm. Elements 72 and 74 also have respective reflectivities R_{G1} and R_{G2} . Elements 72 and 74 are also respectively located at distances D1 and D2 from front end 56, and are spaced apart from one another by a distance D3 ($D3 = D2 - D1$). Reflectivity bandwidths B1 and B2 at least partially overlap, and in an example embodiment, completely overlap.

Further in an example embodiment, elements 72 and 74 are narrow-band thin film reflective filters, such as single-channel filters used for dense wavelength 10 division multiplexing (DWDM). Such narrow band thin-film reflective filters are available from Corning, Inc., Endicott, NY.

In another example embodiment, elements 72 and 74 have substantially the same reflectivity, i.e., $R_{G1} = R_{G2} = R_G$, substantially the same reflectivity bandwidth, i.e., $B_1 = B_2 = B$, and substantially the same peak reflectivity at a center wavelength 15 λ_C —in other words, the elements are preferably “matched,” at least to within their design tolerance.

With continuing reference to FIG. 2, system 50 includes three discrete Fabry-Perot (FP) cavities. A first cavity 100 is within laser 52 itself and is defined by rear end 54 and front end 56, and includes gain medium 57. Cavity 100 lases, in 20 the absence of external feedback, at a wavelength and a coherence length defined by the gain medium and laser cavity properties. A second FP cavity 106 is an “external cavity” defined by front end 56 and element 72. A third FP cavity 112 is also an external cavity defined elements 72 and 74.

A key aspect of system 50 involves properly selecting distances D1 and D3 25 (which also determines distance D2 via the relationship $D2 = D1 + D3$). When distances D1 and D3 are properly selected, third FP cavity 112 serves to destroy the coherence of the laser light reflected therefrom through Fabry-Perot interference. This in turn allows distance D1 to be substantially smaller than that of a two-cavity laser system, while still maintaining stable operation of the laser in the coherence 30 collapse regime (and throughout the operating drive current range where laser 52 is a laser diode). In fact, in laser system 50 the distance D1 can be less than the

coherence length of the free-running laser. Further, the distance D2 may also be within the coherence length of the free-running laser if the values D1 and D3 are properly selected.

The appropriate distances D1 and D3 for a given application may best be
5 determined and selected empirically. For example, the different operational modes
(e.g., stable and unstable) of laser system 50 for various laser geometries (i.e.,
distances D1 and D3) may be measured and plotted. The plot reveals regions in
“D1-D3 space” in which the laser operation is stable and where it is unstable. An
example of such a plot is discussed in greater detail below in connection with
10 FIG. 9.

Once the appropriate values for distances D1 and D3 are selected, the
operating wavelength of laser 52 is pulled to and maintained at the center
wavelength λ_C so that system 50 operates in a stable manner, e.g., reduced variation
15 in the output wavelength as a function of temperature variations, drive current
fluctuation and wavelength drift due to aging of the laser.

Alternative optical system embodiments

The laser system 50 of FIG. 2 illustrates an embodiment where optical
system 66 is arranged between the front end 56 of the laser and the first wavelength-
20 selective reflective element 72. With reference now to FIGS. 3-6, there are shown
alternative example embodiments of laser system 50 wherein optical system 66 is
arranged to encompass element 72 only (FIG. 3), is arranged between elements 72
and 74 (FIG. 4), is arranged to encompass element 74 only (FIG. 5) or is arranged to
encompass both elements 72 and 74 (FIG. 6). Further, combinations of the above
25 geometries of optical system 66 illustrated in FIGS. 2-6 are possible. For instance,
as one example, optical system 66 may include multiple sections, wherein one
section of optical system 66 may be located as illustrated in FIG. 2, while another
section of the optical system may be located as illustrated in FIG. 4.

Optical system 66 may include lens elements, mirrors, optical fibers, etc.,
30 arranged so that light from laser 52 is coupled to elements 72 and 74 and light
reflected therefrom is coupled back into the laser.

FIG. 7 illustrates an example of a preferred embodiment of the laser system of FIG. 6, wherein optical system 66 comprises an optical fiber 126, and laser 52 comprises a diode laser. The laser system of FIG. 7 is now discussed in greater detail to illustrate a particular example embodiment of laser system 50.

5 Optical fiber 126 has an end 130, a core region 136 and a cladding region 140 surrounding the core (FIG. 8). End 130 of optical fiber 126 is optically coupled to laser 52 at front end (facet) 56 so that light from the diode laser enters the optical fiber and is guided thereby. The optical coupling is performed using any one of a number of known techniques, including butt-end coupling, coupling with a separate 10 lens, or coupling via a polished optical fiber end acting as a lens integral with the optical fiber. In an example embodiment, optical fiber 126 is single-mode optical fiber. In another example embodiment, optical fiber 126 is Corning Flexcore-1060, available from Corning, Inc., Corning, NY.

15 In laser system 50 of FIG. 7, wavelength-selective reflective elements 72 and 74 are formed in optical fiber 126. In an example embodiment, elements 72 and 74 are narrow-band thin-film filters. In another example embodiment, elements 72 and 74 are Bragg gratings formed in core 136 or cladding 140 of optical fiber 126. Regardless of the type of wavelength-selective reflective elements used, the light 20 guided by fiber 126 is selectively reflected by the elements back toward diode laser 52 to provide incoherent optical feedback to the laser.

As discussed above, optical fiber 126 may be coupled to front facet 56 of diode laser 52 by placing optical fiber end 130 in close proximity to the front facet (e.g., butt-end coupling). In this case, distance D1 will be substantially the same as if measured from optical fiber end 130. Alternatively, the optical coupling of 25 optical fiber 126 to front facet 56 using a lens (not shown) may leave a significant gap G between the front facet and optical fiber end 130. In this case, element 72 is formed a predetermined distance D4 from optical fiber end 130 to ensure that distance D1 is the desired distance when optical fiber 126 is coupled to diode laser 52 (i.e., $D1 = G + D4$).

Determining the operation modes of the laser system

The different operational modes (e.g., stable and unstable) of the laser system may be determined empirically by making measurements of the operational state of the laser for various laser geometries (i.e., distances D_1 and D_3) and plotting the results. The plot reveals regions in “ D_1 - D_3 space” in which the laser operation is stable and where it is unstable so that the appropriate distances D_1 and D_3 can be selected.

10 FIG. 9 is a plot of the operational modes of laser system 50 of FIG. 7, with fiber Bragg gratings as the wavelength-selective reflective elements 72 and 74. In obtaining the data plotted in FIG. 9, experiments were performed for a matrix of distances D1 and D3, where distance D1 was varied between 20, 30, 40 and 50 cm, while distance D3 was varied between 2.5, 5, 10, 20 and 30 cm. The experiments involved splicing together different lengths of optical fibers containing fiber Bragg gratings to obtain an optical fiber with the desired element spacings. The optical fiber was then coupled to the diode laser and measurements of the drive current vs. output power were made.

In FIG. 9, it can be seen that for a distance D_1 of 30 cm, stable operation of the diode laser occurs when distance D_3 is between 20 cm and 30 cm. If the distance D_1 is increased to 50 cm, then stable operation of the diode laser occurs when the distance D_3 is as small as 5cm. However, if distance D_3 is decreased to 2.5 cm, the operation of the diode laser will be unstable.

It is important to note that because elements 72 and 74 can be positioned closer to diode laser 52 than a single element, the effect of birefringence-induced polarization rotation from the optical fiber is substantially reduced. This allows for the use of standard optical fiber instead of the specialized and more expensive polarization-maintaining fiber.

Also, with reference again to FIGS. 3-6, optical fiber 126 can be coupled at one end to the laser and terminated at or near wavelength-selective reflective element 72 so that there is guided-wave propagation of light to wavelength-selective reflective element 72 and free-space propagation of light to wavelength-selective reflective element 74. Likewise with reference to FIG. 4, optical fiber 126 can be

arranged between elements 72 and 74 so that there is mostly or all free-space propagation from the laser to element 72 and then mostly or all guided-wave propagation between elements 72 and 74. With reference to FIG. 5, guided-wave propagation can be continued beyond element 74 by including element 74 as well 5 by extending the optical fiber beyond this element. Thus, the various possible alternative arrangements of laser system 50 allows for a given laser system to include different types of wavelength-selective reflective elements, such as one fiber Bragg grating and one thin-film reflective filters, as well as utilize different forms of lightwave propagation (e.g., free-space or guided-wave).

10

Optical telecommunications system

With reference now to FIG. 10, there is shown a portion of a fiber optical telecommunications system 200 in which the laser system 50 of FIG. 7 serves to energize an active element 202 optically downstream of the laser system. In an 15 example embodiment, element 202 is included in an optical fiber 206 that is coupled to optical fiber 126 at an end 208 opposite end 130 via an optical coupler 212. Optical coupler 212 may be, for example, a wavelength-division multiplexer (WDM). Element 202 may be, for example, an erbium-doped fiber amplifier (EDFA) that is energized (i.e., pumped) by the light from optical fiber 126. Element 20 202 may be arranged to receive an input signal 220 traveling along a section of optical fiber 226 that is also coupled to optical coupler 212. Element 202 then processes (e.g., amplifies, in the case of an EDFA element 202) input signal 220 to form an output optical signal 228.

Element 202 may also be a fiber laser having a pumping bandwidth at or 25 near 980 nm. Optical signal 220 may include a plurality of channels (i.e., different multiplexed wavelengths of light).

An advantage of the use of diode laser system 50 of the present invention as part of telecommunication system 200 is that the length of optical fiber 126 can be significantly shorter than that used with a conventional diode laser system.

30 With reference now to FIGS. 11A and 11B, there are shown plots of the output power vs. drive current (FIG. 11A) and RFM current vs. drive current (FIG.

11B) for an example embodiment of laser system 50 where laser 52 is a diode laser having a nominal front facet reflectivity $R_{FF} = 4\%$. For a single element 72 in the form of a fiber Bragg grating having a reflectivity R_{GI} of 3.4% and positioned such that distance $D1 = 50$ cm (dashed curve), the power and RFM current show two 5 large instability regions 240 and 242 below the kink current 244 (at about 240 mA). It is typical that instabilities show up stronger in the RFM signal (FIG. 11B) measured at rear facet 54 than in the output power (FIG. 11A) measured at front facet 56. However, the issue of instabilities is important because monitor 60 is used to monitor output power and provide feedback to drive current supply 58 to control 10 the drive current in order to maintain a constant output power.

A second reflective element 74 in the form of a fiber Bragg grating nearly identical to the first fiber Bragg grating 72 was then added at a distance $D3 = 10$ cm from the first fiber Bragg grating to create third cavity 112 in forming laser system 50 of FIG. 7. This laser system 50 operated in a stable condition throughout the 15 drive current range (dotted curve). To demonstrate that the stability was not induced by simply increasing total reflectivity (which is 6.4 % for cavity 112), a single fiber Bragg grating of the same reflection bandwidth and peak wavelength of the first two, but with a reflectivity $R_G = 6.5\%$ was spliced and placed at a distance $D1 = 50$ cm. This higher reflectivity single fiber Bragg grating arrangement (solid 20 curve) still exhibited instabilities 260 and 262 similar to instabilities 240 and 242 of the single fiber Bragg grating arrangement having 3.4% reflectivity (dashed curve).

Therefore, it is clear that the three-cavity laser system 50 enables stable operation in the coherence collapse regime in a manner different than that achieved by simply changing the feedback reflectivity of a two-cavity laser system.

25 While the present invention has been described in connection with preferred embodiments, it will be understood that it is not so limited. On the contrary, it is intended to cover all alternatives, modifications and equivalents as may be included within the spirit and scope of the invention as defined in the appended claims.